

# **L-Series**

#### **Position Controller**

### **Applications**

The L-Series Position Controller provides a building block approach to total engine management. The microprocessor-based bi-directional actuator design easily attaches to fuel pumps, mixers, or throttle bodies.

### **Description**

The L-Series Position Controller accepts a position command and drives the 0–60 degree output shaft to the commanded position based on an internal shaft position sensor. The high-efficiency torque motor delivers 0.34 N·m (0.25 lb-ft) nominally over 60° travel range to operate fuel or air control devices (see specifications for torque performance over the full product temperature range).

The L-Series Position
Controller accepts either a
PWM, 0–5 V, or CAN
command for output
positioning. The command
signals are issued by the
appropriate supervisory engine
management system, and the
L-Series must be set up
properly in software to expect
the correct signal for the
application.

For status purposes, a relay driver output is available on the

L-Series control which changes state whenever a fault or error condition is experienced by the controller.

The L-Series provides a direct position output signal in the form of a dc voltage if required by the system. The throttle position (TPS) output represents full counterclockwise-to-clockwise rotation of the actuator shaft, and thus gives the operator an external position indication.

Besides the traditional bracket mount using external linkage, the L-Series control is available in a variety of mechanical configurations, including integration with diesel fuel pumps, throttle bodies, and mixers (product spec 03222). The shaft rotation can be configured for clockwise or counterclockwise rotation for increasing fuel. For information on Woodward throttle body applications, refer to manual 26249 (ITB and LC-50).

Woodward offers optional mounting kits for Stanadyne DB-series or Delphi fuel injection pumps, providing an integrated control solution.

Woodward also offers L-Series actuator versions for Speed Control (manual 26250) and Process Control (manual 26251), like Air/Fuel Ratio control, applications.

To learn more about the new L-Series actuators, contact Woodward today.

**Technical Manual** 26237 (standard) or 26289 (w/ CAN)



- Low cost, small package actuator
- Extremely fast, bi-directional, electronically positioned in both directions
- All-electric actuator requires no drive or hydraulic supply
- 60° (±2°) rotary output
- Single or redundant position command signals
- Advanced diagnostics
- Tamper-resistant
- Configurable parameters to tailor to varied applications
- Easy setup and tuning using PCbased Service Tool
- Optional CANopen and J1939 CAN communications

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## **Specifications**

Power Supply 12/24 V systems (10-32 Vdc) reverse polarity protection

**Power Consumption** 32 W maximum

> Envelope 2.618" x 2.618" x 2.540" (66.50 x 66.50 x 64.52 mm)

Travel 60 ±2 degrees

Torque Nominal: 0.34 N·m (0.25 lb-ft) at 25 °C

Maximum Transient (at 105 °C): 0.20 N·m (0.15 lb-ft) Minimum Continuous (at 105 °C): 0.14 N·m (0.10 lb-ft)

Mass/Weight 425 g (15 oz)

PWM (5-32 V, 300-1500 Hz), CAN, or Analog (0-5 V) Command Input

Position Feedback Output 0.75 V (full ccw) to 4.25 V (full cw)

> Discrete Input Optional Run Enable

Discrete Output Low side output driver; software configurable

Programmable with Windows<sup>®</sup> GUI software (9927-1222) and harness (8923-1061) **Programming Port** 

**Performance** 

Positioning Accuracy ±2% at 25 °C

±4% (analog), ±3.6% (PWM), ±3% (CAN)—over temp. range

Slew Time 10%-90% 33 ms, 1% overshoot, 10 ms settling time

Roll-off 32 Hz (-6 dB at ±0.5% Input), 8 Hz (-3 dB at ±2% input)

**Environment** 

-40 to +105 °C (-40 to +221 °F) Operating Temperature -40 to +125 °C (-40 to +257 °F) Storage Temperature

**EMC** 

EN61000-6-2: Immunity for Industrial Environments EN61000-6-4: Emissions for Industrial Environments

SAE J1113-21: Radiated Immunity (100 V/m) SAE J1113-11: Conducted Transient Immunity -

Pulse 5b, Suppressed Load Dump (45 V)

Humidity US MIL-STD 810E, Method 507.3, Procedure III Shock MS1-40G 11ms sawtooth

Random: 0.3 G2/Hz, 10-2000 Hz (22.1 Grms) 3 h/axis Vibration

Sine: 5 G 2.5 mm peak-to-peak, 5-2000 Hz, 3 h/axis,

90 min dwells, 1 octave/min

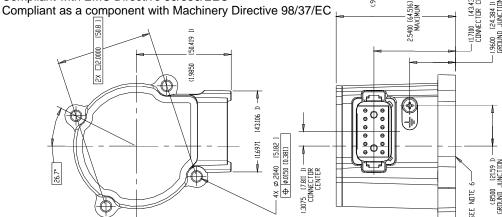
Thermal Shock SAE J1455, Paragraph 4.1.3.2

Fluid Resistance IP56 per EN60529

Compliance

CSA Class I, Division 2, Groups A, B, C, D T3C Compliant with EMC Directive 89/336/EEC CE

Other





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